

4-quadrant controller
Technical reference
multicomp

F144-MS-1V1C1TI6RO-3 F144-MS-1V1C1TI12RO-3


Your partner for
network analysis
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network analysis
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1 Functional principle
of the controller
.8
2 Control and display panel ..... 10
3 Setting range of the configurable parameters: ..... 14
4 Installation and electrical connection of the system ..... 16
4.1 General, very important information ..... 16
4.2 Current transformer connection and measuring voltage ..... 17
4.3 Current transformer dimensions ..... 17
4.4 Standard connection diagram: ..... 18
5 Commissioning the system ..... 20
5.1 General notes on commissioning ..... 20
6 Navigation and device displays ..... 22
7 Device displays of the main menus ..... 24
8 Description of the individual dis- play windows ..... 26
8.1 Initialization window: ..... 26
8.2 Commissioning window if no stage power is programmed: ..... 26
8.3 Start menu window: ..... 29
8.4 Stage state window: ..... 31
8.5 Service window: ..... 32
8.6 Commissioning window: ..... 33
8.7 Switching performance window: ..... 36
8.8 Error message window: ..... 38
8.9 Extras window: ..... 39
9 Notes on troubleshooting ..... 43
10 System and safety device maintenance ..... 44
11 Technical data ..... 45
11.1 Measuring and display values ..... 45
11.2 Measuring accuracy ..... 46
11.3 Measuring principle ..... 46
11.4 Device memory ..... 46
11.5 Other limits: ..... 46
11.6 Power supply ..... 46
11.7 Hardware inputs and outputs ..... 47
11.7.1 Hardware inputs ..... 47
11.7.2 Hardware outputs ..... 47
11.8 Electrical connection ..... 48
11.9 Mechanical data ..... 49
11.10 Standards and miscellaneous. ..... 49
12 Selection of cables and fuses. ..... 50
13 Data point description for the Modbus protocol ..... 52
13.1 Supported Modbus commands.. ..... 53
13.2 Data formats ..... 53
13.3 Interface parameters ..... 56
13.4 Device settings ..... 56
13.5 Data points ..... 62
13.6 Device information ..... 65

## Dear customer

Thank you for choosing a KBR product.
To familiarize yourself with operation and configuration of the device, we recommend that you read this manual carefully. This will enable you to make use of the entire range of functions that this high-quality product offers.

The individual chapters serve to explain the technical details of the device and show how to properly install and start up the device to prevent damage.

This user manual is included in the scope of delivery of the device and must be accessible to the user at all times (e.g. in the switchgear cabinet). Even if the device is resold to third parties, the manual remains an inherent part of the device.

Although the utmost care has been taken in putting together this user manual, errors may still occur. We would be very grateful if you could notify us of any errors or unclear descriptions you may notice. The form included in the appendix to this manual can be used to send us corrections or suggested improvements.

Yours sincerely,
KBR GmbH Schwabach

These operating instructions contain notes that must be observed for your personal safety and to avoid damage to equipment. These instructions are identified by a warning sign or information symbol, depending on the degree of hazard they represent.

## DANGEROUS VOLTAGE

means that death, major injury or substantial property damage may occur if the appropriate safety measures are not taken.


CAUTION
means that minor injuries or property damage may occur if the appropriate safety precautions are not taken.


## NOTE

is an important piece of information on the product, product handling or the respective part of the user manual to which special reference is made.

## Disclaimer

The contents of this manual have been checked with the described hardware and software components. However, deviations may occur so that no guarantee can be made for complete agreement with the documentation. The specifications given in this manual are checked on a regular basis; necessary corrections will be included in the next revision.

We appreciate your corrections and comments.

## Safety notes

In order to prevent operating errors, handling of the device has been kept as simple as possible. This will enable to use the device very quickly. In your own interest, however, the following safety notes should be read carefully.

## DANGEROUS VOLTAGE

## The applicable DIN/VDE regulations must be observed for installation!

Power supply connection, setup and operation of the device may only be performed by qualified personnel. Qualified personnel as defined in the safety notes in this user manual are personnel with electrical engineering qualifications, knowledge of the national accident prevention regulations and safety engineering standards as well as of the installation, commissioning and operation of the device.
To reduce the risk of fire or shock hazard, the device must not be exposed to rain or humidity!
Before connecting the device to the power supply, check whether the local power supply conditions comply with the specifications on the device nameplate.
A faulty connection may result in the destruction of the device!
When connecting the device, ensure that the data given in the connection chart is complied with (see "Connection diagram") and that the connection cables are not live. When wiring, always ensure that all wiring material used is neither damaged nor defective and that the polarity is correct!
In order to ensure proper and safe product operation, ensure that the device is transported, stored, installed and assembled and carefully operated and maintained in accordance with the specifications.
A visibly damaged device must generally be considered unfit for use and disconnected from the power supply. Troubleshooting, repairs and maintenance work may only be carried out in our facilities or after contacting our service team.
Unauthorized opening of the the device will render your warranty null and void. Correct operation can no longer be guaranteed!
Opening the device may expose live parts. Capacitors in the device may still be charged, even if the device has been disconnected from all sources of electricity. Do not operate open devices under any circumstances!
Systems that are at risk from lightning strikes must be fitted with lightning protection for all input and output cables (see chapter "Protective measures" for recommendations).

## Product liability

## You have purchased a high-quality product.

Only components of the highest quality and maximum reliability are used.
Each device is subject to long-term testing before it is delivered.
For details on product liability, please refer to our
general terms and conditions for electronic equipment.
The assured device properties only apply if the device has been operated in accordance with its intended use!

## Disposal

Devices that are faulty, now obsolete or no longer used must be properly disposed of.

If required, we will dispose of the devices for you.

## 1 Functional principle of the controller

The controller's microprocessor records the mains voltage and current consumption of the entire company via measuring transformer inputs (A/D converter) and calculates the active and reactive power ratio of the power supply. The controller operates in four quadrants.

■ Energy recovery in generator operation is detected and indicated by a "G" flashing on the LCD display. During this time, compensation to cos phi 1.00 (output cos phi) is performed. To prevent alternating switching operations, this target cos phi is maintained for 15 minutes after generator operation.

The compensated power required for the target cos phi is calculated continuously. If the power difference corresponds to the set hysteresis (switch-on and switch-off hysteresis), the stages are switched depending on the required compensation power. Manually switched stages are, however, not included in the optimization. In case of identical stages with identical power, the stage that has been switched off for the longest time is switched on.

Having fewer switching operations results in an optimum adjustment. Even for large systems, sensitive controls may be set up with only a few modules. Stage ratios do not have to be considered. After compensation, switching operations are interrupted for a programmable time. To prevent alternating switching operations, you can increase the stage switch-off delay by up to $150 \%$ of the smallest stage's power.

In low load operation (secondary measuring current under the limit), the stages are switched off after the sett delay time.

The integrated temperature measurement input monitors the temperature in the reactive power compensation system and triggers the fan to be switched on if a predefined limit temperature is exceeded and switched off again when the temperature drops below the reset temperature.

To prevent unnecessarily frequent switching of the fan, it has a run-on time of 30 minutes. You can switch the fan (relay output 6 or 12 depending on the device version) on or off permanently using the "Stage status" menu. If you select "Auto", the fan output is controlled by the temperature measuring input.

Furthermore, you can protect the system by defining a switch-off temperature. This makes it possible to switch off stages in time if there is a risk of damage due to overtemperature. If the reset temperature is exceeded, the stages are switched on again one after the other.

The settings are saved on an EEPROM so that they are not lost in the event of a power failure.

The measuring cycle of the controller for recording the necessary network parameters takes approx. 20 ms .

## NOTE

Limit for overvoltage switch-off $=$ measuring voltage $+10 \%$ (taking the measuring voltage ratio into account). This value cannot be changed and serves to protect the compensation system. In the event of an error, the compensation stages are switched off and "Overvoltage" is displayed.

## CAUTION

The discharge times are automatically predefined for the following programmed stage powers. However, these must be checked and corrected if they differ from the capacitor specifications.

| Capacitor <br> power | Discharge <br> resistance | Discharge time |
| :--- | :--- | :--- |
| 0.1 kvar -9.9 kvar | 300 kOhm | 60 seconds |
| 10 kvar -19.9 kvar | 300 kOhm | 120 seconds |
| 20 kvar and above | 300 kOhm | 180 seconds |

## 2 Control and display panel

multicomp F144-MS-1V1C1TI6RO-3

multicomp F144-MS-1V1C1TI12RO-3


## Operating elements:

1 LCD displaying the current status and user prompts
2 Number of possible controller output lines
3 Two sensor buttons for parameter configuration
4 Two sensor buttons for menu selection

## General notes on operating the sensor buttons:

| $\boldsymbol{\pi}$ button | Start configuration and reset input |
| :--- | :--- |
| button | Change values during configuration |
| button | Navigation though submenus |
| bavigation through main menus and save button during configura- |  |
|  | tion |

## Button combinations:

$$
\boldsymbol{\lambda} \text { and buttons Delete accumulated values and perform reset }
$$

## Default controller settings after reset:

## Commissioning menu

- Consumption target cos phi:
- Recovery target cos phi:
- Alarm cos phi:
- Main transformer current:
- Measuring voltage:
- Rot. field U:
- Rot. field I:
- Current attenuation coefficient:
- Voltage attenuation coefficient:
- Attenuation coefficient Qmiss:
- Alarm delay:
- Idle time:
- Switching interval:
- Hysteresis connection:
- Hysteresis switch-off:
- Operating cycle limit:
- Operating cycle count:
- Stage switching mode:
0.95 inductive
1.00 (cannot be changed)
0.92 inductive

Primary current 1000 A
Secondary current 5 A
Primary voltage 400 V Ph-Ph (corresponds to 230 V Ph-N)
Secondary voltage 400 V Ph-Ph (corresponds to 230V Ph-N)
L1-N
L1
2
2
2
20 minutes ( 1200 seconds)
30 seconds
8 seconds
100\% of lowest stage power
$100 \%$ of lowest stage power
80000
Activated by set limit
Automatic

- Sampling rate:
- Harmonics monitoring:
- THD limit:
- Stage power:
- Stage power monitoring:
- Discharge time:
- Password:
- Language display:
- Contrast setting:
- Brightness setting:
- Dimmer brightness:
- Low-load limit:
- Low-load delay:
- Temperature measurement:
- Relay 6/12 as stage or fan:
- Fan switch-on temperature:
- Fan switch-off temperature:
- System switch-off temperature:
- System switch-on temperature:
- Learning mode menu display:
- Key sounds:


## Error message dialog after reset:

No measuring voltage:
No stage power:
PFC too small:
THD too high:
Operating cycle limit exceeded:
No measuring current:
Low load operation:
Temperature switch-off:

## Automatic

Activated by set limit
8\%
Not set
Deactivated
180 seconds
No password
(9999, meaning all functions are accessible)
English
5
5
0
15 mA
60 minutes
On
Fan relay
$>28^{\circ} \mathrm{C}$
$<23^{\circ} \mathrm{C}$
$>48^{\circ} \mathrm{C}$
$<43^{\circ} \mathrm{C}$
Off
On

Message and alarm relay
Message and alarm relay
Message and alarm relay
Message and alarm relay
Message and alarm relay
Message and alarm relay
Message and alarm relay
Message and alarm relay

The controls in the compensation systems are preset.

The following need to be checked or set:

- Target cos phi in accordance with the electricity supplier regulations (for kVA tariff $\cos p h i=1$ )
- Primary current and secondary current in accordance with input current transformer.
- Voltage transformer ratio, if required



## NOTE

Upon delivery, the bus protocol is set to: Modbus RTU, baud rate 38400, parity even. This setting can only be changed manually on the device. However, performing a "Reset to default settings" has no effect on a changed setting.

## 3 Setting range of the configurable parameters:

## Stage status:

Stage switching mode

Commissioning:
Password
Primary current
Secondary current
Consumption target $\cos \varphi$
Recovery target $\cos \varphi$
Primary voltage
Secondary voltage
Rot. field U
Rot. field I
Stage power learning mode
Stage power
Discharge time

## Switching performance:

| Hysteresis connection | 70 to $150 \%$ |
| :--- | :--- |
| Hysteresis switch-off | 70 to $150 \%$ |
| Alarm relay time | 3 to 3000 sec. |
| Idle time | 0 to 300 sec. |
| Switching interval | 0 to 10 sec. |
| FTS alarm $\cos \varphi$ | ind. 0.70 to 1.0 |
| Attenuation coefficient $Q_{\text {miss }}$ | 0 to 9 |
| Voltage attenuation coefficient | 0 to 9 |
| Current attenuation coefficient | 0 to 9 |

## Error message dialog:

No measuring voltage The settings Message or
No stage power
PFC too small
THD too high Alarm relay or Message and Error message relay or Off is identical for all errors!

Operating cycle limit exceeded
No measuring current
Low load
Temperature switch-off

Extras:

| Display language | German, English, French, Spanish |
| :---: | :---: |
| THD limit | 0 to 10\%, harmonics monitoring can be disabled (0\%) |
| Operating cycle limit | 0 to 999999 (0 = deactivated) |
| Scanning frequency | Automatic, fixed 50 Hz , fixed 60 Hz |
| Stage power monitoring | Yes, No |
| Reset | Run |
| Contrast setting | 0 to 10 |
| Brightness setting | 0 to 9 |
| Dimming brightness | 0 to 9 |
| Low-load limit | $15 \mathrm{~mA}, 50 \mathrm{~mA}$ |
| Low-load delay | 1 minute to 60 minutes |
| Temperature measurement | On, Off |
| Relay 6 or 12 (depending on the controller version) | Compensation stage, fan relay |
| Fan switch-on temperature | $>0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ |
| Fan switch-off temperature | $0^{\circ} \mathrm{C}$ to $70{ }^{\circ} \mathrm{C}$ |
| System switch-off temperature | $>0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ |
| System switch-on temperature | $0^{\circ} \mathrm{C}$ to $70{ }^{\circ} \mathrm{C}$ |
| Bus mode | Modbus (eBus for production) |
| Learning mode menu display | On / Off |
| Key sounds | On / Off |

## 4 Installation and electrical connection of the system

### 4.1 General, very important information

- Tighten all screws and connections. Failure to do so will void the warranty.
- Install and operate the device in accordance with the applicable VDE regulations (in particular VDE 0100) and the electricity supplier regulations.
- Connection cross-sections and fuse protection table: see annex.


## CAUTION

Failure to observe the connection conditions or exceeding the permissible voltage range may result in damage or destruction of the device.

Before connecting the power supply to the device, please note:

- The voltage and frequency must comply with the specifications on the nameplate. Observe the limits specified in this manual!
- A disconnector or circuit-breaker must be provided for the power supply voltage in the building installation, in accordance with the applicable local regulations.
- Install an isolating switch that is easily accessible to the user and close to the device. It must be marked as an isolating switch for this device.
- Install a suitable, correspondingly marked fuse and isolating switch for the voltage measurement inputs nearby (alternative: circuit breaker). These voltages are dangerous to touch!
- Voltages that exceed the permissible rated voltages must be connected using a voltage transformer.
- Measuring voltages and measuring currents must be taken from the same power supply.


### 4.2 Current transformer connection and measuring voltage

If possible, mount the transformer in the phase that corresponds to L1 of the compensation system (determine by means of voltage measurement). All capacitor and consumer currents must be determined. In case of an unbalanced phase load (in small companies), install the transformer in the phase with the highest load.

- P1 (K) to energy supply (indicated on the transformer).
- P2 (L) to load outputs
- S1 (k) with terminal k (controller terminal 20) and
- S2 (I) with terminal I (controller terminal 21) have to be connected in the compensation system (use a two-color cable!).

Wire cross section: up to $3 \mathrm{~m}=1.5 \mathrm{~mm}^{2}$, up to $6 \mathrm{~m}=2.5 \mathrm{~mm}^{2}$. For longer distances, we recommend using a 1 A transformer. The controller is designed for connection to 5 A and 1 A transformers; switching is done by firmware.

If using existing transformers, the current paths always need to be connected in series. The secondary transformer current needs to be at least 15 mA . For lower currents, no capacitors are connected (display shows "Missing current"). Measuring voltage connection according to the connection diagram.

### 4.3 Current transformer dimensions

The current transformer is designed on the basis of the current consumption of the consumers, not the capacitor current. If, in addition to the reactive power controller, other measuring devices are connected to the same transformer, the transformer power needs to be chosen accordingly. Losses also occur in the current transformer cable that need to be considered if there are long distances between the transformer and the controller.

### 4.4 Standard connection diagram:



## Connection measuring voltage

Ph-Ph


## 5 Commissioning the system

### 5.1 General notes on commissioning

The controller is preset as a compensation system component (see connection diagram). The following need to be configured or checked:

- Target cos phi according to electricity supplier specifications.
- Primary and secondary current in the main circuit according to the transformer fitted.
- Set the measuring voltage transformer data, if necessary.
- If no stage powers have been programmed, the controller will switch to the Commissioning menu after initialization. Next, stage power programming can be performed in the settings menu, or using the learning process.

NOTE

You can start the learning process from the Activate learning mode? submenu in the Commissioning menu, using the Enter/Input buttons. If the "Learning mode" window is not displayed, please check the following:

- is Menu on set for "Learning mode" in the "Extras" menu?

The settings are saved on an EEPROM so that they are not lost in the event of a power failure.

- Switch on a sufficient number of inductive consumers (e.g. motors) before switching the compensation system on. A transformer current of at least 15 mA needs to be flowing in the secondary circuit for the controller to be activated. Below this limit, the display will show "No transformer current". Check the transformer connection (transformer ratio too high?).
- If all connection conditions are OK, the instantaneous power factor cos phi should appear on the display after initialization, e.g. Normally, when no capacitors are connected, cos phi lies in the range of 0.6 to 0.9 inductive, (e.g. cos phi 0.80 ind).
- If a capacitive value is displayed, or if the "G" symbol is flashing, the phase allocation of the current and voltage measurement is incorrect. In the Commissioning programming menu, the phase allocation can be changed using the functions Rot. field $U$ and Rot. field I (provided that there is no generator operation at the time).
- The first switching operation may take up to 180 seconds. The stages are switched in a set intervals until compensation occurs. The displayed cos phi must increase to at least the set target cos phi.


## 6 Navigation and device displays



$\downarrow$

-

$\nabla$



Start menu
$D$


## 7 Device displays of the main menus

Different main menus and submenus can be used for current displays and controller configuration.

Initialization menu - no input possible
multicomp F144-3 6-stage or 12-stage

> multitome be evo Initiglize

```
multicomf 12 emo
    Initielize
```

Start menu window - display of the current values multicomp F144-3 6-stage

```
Ems% 0.71 IHD
```


## AMAMAF

multicomp F144-3 12-stage

$$
\begin{aligned}
& \text { mमпनmannanma }
\end{aligned}
$$

Stage state window - stage status can be changed

$$
\begin{gathered}
\text { stege }=t \mathrm{ta} \\
\text { next } 4 \mathrm{t}
\end{gathered}
$$

Service window - display and deletion options


Commissioning window - entry of operating parameters

## Gommis si onine

next $4+$

Switching performance window - influencing switching performance

## Suitehrerform.

 next 4 *Error message menu - editing the error message dialog
Messene menu next $4 \rightarrow$

Extras window - setting special parameters

## Extres

mext. $4 \div$

## 8 Description of the individual display windows

### 8.1 Initialization window:

multicomp F144-3 6-stage or 12-stage
multivomp be eot
Initielizetion
multicome 12 evo
Ini ti alizetion
This is displayed after connecting the power supply to the controller.

## NOTE

Please do not press any sensor buttons during initialization; they are adjusted automatically to ensure correct operation.

### 8.2 Commissioning window if no stage power is programmed:

$$
\begin{gathered}
\text { Comm }= \pm \text { mine } \\
\text { net. } 4 ;
\end{gathered}
$$

During initial startup of the multicomp F144-3, the Commissioning menu is displayed as the F144-3 start screen (after the initialization phase) once you have connected the power supply.
This menu is used for initial startup of the controller, where all necessary settings can be set.
If you wish to use a controller that is already integrated into a KBR compensation system by default, only the parameters of the current transformer need to be configured.
Press
to select submenus.

## Password protection:

A password can be entered (4-digit number code, e.g. 4321) to protect a system against unauthorized access of the configured parameters.

If the password is lost, the controller can be unlocked using the master password 1976. To unlock a controller completely, enter the password 9999 (no password = 9999, all functions are accessible).
When unlocking a password-protected controller, it is possible to press a button for up to 300 seconds. If no button is pressed during this period, the controller is locked again.
The password can be configured by pressing $\boldsymbol{\lambda}$ to start entering and changing the entry position, the thange or set the value and $\boldsymbol{D}$ to save the entry.

## Configuring current transformer values:

For the compensation controller to function properly, all current transformer parameters need to be set correctly. The primary and secondary current of the transformer need to be set (submenu Iprim. / Isec.). These parameters can be read on the nameplate of the current transformer. In addition, the phase allocation of the transformer needs to be set correctly. In the controller, the phase (L1, $\mathrm{L} 2, \mathrm{~L} 3$ ) in which the current transformer is integrated has to be set (submenu Rot. field I). If the transformer connections are mixed up (k and I interchanged), this can be corrected with the setting -L1, -L2 and -L3.

## Setting target cos phi:

You can ask your electricity supplier for the target cos, which should be set up at this point. By default, the target cos is set to 0.95 inductive (see chapter Default settings).

## Setting the voltage transformer parameters:

Specify the primary voltage in the U primary submenu, the secondary voltage under $\mathbf{U}$ secondary and the phase allocation of the measuring voltage under Rot.field U. These settings apply to a standard mains network (voltage Ph-Ph: 400 V primary, 400 V secondary). If you use a voltage transformer, configure the parameters indicated on the voltage transformer, e.g. $690 \mathrm{~V} / 100 \mathrm{~V}$, as well as the measuring mode, e.g. L12 for measuring voltage connection between phases L1 and L2.

## Setting the discharge time:

Checking or, if required, changing the discharge time of the capacitor stages is a very important menu item. You can set the discharge time from 0 to 999 sec . Please make sure that the correct value is set, otherwise the capacitors could be damaged.

## Configuring the capacitor stages:

There are two ways of configuring the capacitor stages. The stages can be configured manually or using the auto configuration mode.


## NOTE

The Auto configuration mode menu will not appear

- if the "Learning mode" is switched off in the "Extras" menu

It is important to set the stage power correctly. The stage power can be looked up on the nameplate of the stage or the circuit diagram and then programmed manually. In this case, skip the menu item "Activate learning mode" and enter the power value for each stage individually.
If you want to activate the learning mode, ensure that all previous submenu parameters have been set correctly.
The learning mode is activated by pressing $\boldsymbol{\lambda}$. Change to Yes by pressing and confirm by pressing . The auto configuration mode then automatically sets the stage powers and discharge times. However, these values need to be checked after the learning process has been completed.

## NOTE

If an error occurs in the auto configuration mode (harmonics exceeding the limit, measuring voltage too high, missing measuring voltage), the process is interrupted and "Auto configuration mode - Error" is displayed. The auto configuration mode can be restarted once the cause of the error has been rectified.

## System function test:

A function test should be performed after all values have been programmed step by step. To do so, the controller has to be disconnected from the power supply for a few seconds.

After it is reconnected to the power supply, the controller should start automatically. If the $\cos \varphi$ voltage is read in the start menu immediately after switching it on, the value for $\cos \varphi$ should be low and inductive. After approx. 60 seconds, the controller starts to switch on the individual capacitor stages.

The $\cos \varphi$, which can be read in the start menu, should have risen in comparison to its previous value, or it should rise when switching on additional stages. If the compensation system is designed correctly, the controller should compensate to the set target cos phi after a while.

### 8.3 Start menu window:

Example: F144-3 12-stage

$$
\begin{aligned}
& \text { שest b. } \mathrm{E} \text { THD } \\
& + \text { लीn }
\end{aligned}
$$

This is displayed after the initialization window if the stage power has already been programmed. Here, the current total controller state and the currently measured CosPhi are measured.

## Example:

Line 1: currently measured CosPhi 0.71 inductive
Line 2: the controller switches on stages; stages 1 to 4 are already switched to automatic operation, where:

| + | stages are switched on as compensation power is required. |
| :---: | :--- |
| $\boldsymbol{4}$ | stages are switched off due to overcompensation. |
| $\boldsymbol{H}$ | the stage has been switched to automatic operation. |
| $\boldsymbol{A}$ | the stage has been switched on manually. |
|  | the stage has been switched off manually. <br> tigured value (stage monitoring activated, see the Stage monitoring <br> submenu of the Extras menu) |

Press
to select submenus.

## The current readings are displayed in the submenus:

Measuring voltage in volts depending on the selected connection type (Commissioning menu, Rot. field U submenu) in $\mathrm{Ph}-\mathrm{N}(\AA)$ or $\mathrm{Ph}-\mathrm{Ph}(\AA)$.

Main series transformer apparent current in amps (single-phase value).
Apparent power in kVA, projected as a 3-phase value (provided the network load is symmetrical).

Active power in kW, projected as a 3-phase value (provided the network load is symmetrical).

Reactive power in kvar, projected as a 3-phase value (provided the network load is symmetrical).

Compensation power to achieve the set target cos phi missing.
The missing compensation power is displayed up to a maximum value of 9999.9 kvar. If the value exceeds this limit, 9999.9 kvar is displayed

Power frequency in Hz
THD (Harm. U total) in \%, decisive for setting the THD limit (Extras menu, THD limit submenu)

Current temperature reading (if temperature measurement is activated; if measurement is deactivated, $---{ }^{\circ} \mathrm{C}$ is displayed)

Number of overtemperature switch-offs (if temperature measurement is activated; if measurement is deactivated, $---{ }^{\circ} \mathrm{C}$ is displayed)

The firmware version of the controller, e.g. V 2.00R001, is important for support requests, as it can be used to deduce possible changes made to the device firmware.

### 8.4 Stage state window:

$$
\begin{gathered}
5+5=t=t= \\
n=x+4
\end{gathered}
$$

Press to select submenus.

The submenus of this window display whether or not the capacitor stages connected are working in automatic mode, or if they are switched on or off permanently. The individual capacitor stages can be selected by pressing $\boldsymbol{\nabla}$.

You can change the stage state from Aut.e (Automatic) to $\mathrm{Tf}+$ (switched off permanently) orm (switched on permanently) by pressing $\boldsymbol{\lambda}$ to start entering values, ${ }^{2}$ ? to make changes or $\boldsymbol{\nabla}$ to save them.

## NOTE

Capacitor stages that are permanently switched on or off are not available to calculate the optimizing automatic operation.

### 8.5 Service window:

$$
\begin{aligned}
& \text { Erut } \\
& \text { mext } 4
\end{aligned}
$$

Press $\boldsymbol{\nabla}$ to select submenus.
The number of connections of each individual capacitor stage are displayed in the submenus of this window,. You can delete the accumulated operating cycles for all stages by selecting the Delete operating cycles menu item and pressing $\boldsymbol{\sim}$ and ${ }^{[23}$ simultaneously.

If the number of operating cycles of a stage equals or exceeds the value set in the menu item Extras / Operating cycle limit, a message is displayed, depending on the Operating cycle limit exceeded setting in the Error message menu.

In addition, the value in the menu item Missing comp. power maximum can be deleted by pressing $\boldsymbol{\lambda}$ and ${ }^{[2]}$ simultaneously, which resetCompensation units the too small message. If the set target cos phi is not reached despite all available stages being switched on, this message is displayed after the set alarm delay time has elapsed.

The alarm delay can be set in the Switching performance / Alarm delay menu .
You can also delete the number of overtemperature switch-offs here (this menu item is only displayed if temperature measurement is activated and accumulated switch-offs are displayed).

### 8.6 Commissioning window:



Press to select submenus.
A step-by-step description of the setup process is given in the submenus of this window. For systems which are already running, the parameters set during setup can be read out here.

## Password protection:

To protect a system against unauthorized access to the configured parameters, a password (a 4-digit number code, e.g. 4321) can be set.
If the password is lost, the controller can be unlocked using the master password 1976.

When unlocking a password protected controller, it is possible to press a button for up to 300 seconds. If no button is pressed during this period, the controller is locked again.
The password can be configured by pressing $\boldsymbol{\lambda}$ to start entering and changing the entry position, ${ }^{2}$ to change or set the value and $\boldsymbol{D}$ to save the entry.

## Configuring current transformer values:

For the compensation controller to function properly, all current transformer parameters need to be set correctly. The primary and secondary current of the transformer have to be set (submenu Iprim. / Isec.). These parameters can be read on the nameplate of the current transformer. In addition, the phase allocation of the transformer needs to be set correctly. In the controller, the phase (L1, L2, L3) in which the current transformer is integrated has to be set (Rot. field I submenu). If the transformer connections are mixed up ( $k$ and I interchanged), this can be corrected with the setting -L1, -L2 and -L3.

## CAUTION

Changing the main current transformer parameters or voltage transformer values subsequently can directly influence the capacitor stages for which the stage power was determined using the auto configuration mode. This is ensures that the stage power is adequately adjusted in case of a subsequent correction of the transformer parameters.
Manually configured stages are not taken into account here.

## Setting target cos phi:

You can ask your electricity supplier for the target cos phi, which should be set up at this point. By default, the target cos phi is set to 0.95 inductive (see chapter "Default settings").

## Setting the voltage transformer parameters:

Set the primary voltage in the U primary submenu, the secondary voltage under U secondary and the phase allocation of the measuring voltage under Rot.field U. These settings apply to a standard network (voltage Ph-Ph: 400 V primary, 400 V secondary). If you use a voltage transformer, configure the parameters indicated on the voltage transformer, e.g. $690 \mathrm{~V} / 100 \mathrm{~V}$, as well as the measuring mode, e.g. L12 for measuring voltage connection between phases L1 and L2.

## Setting the discharge time:

Checking or, if required, changing the discharge time of the capacitor stages is a very important menu item. You can set the discharge time from 0 to 999 sec . Please make sure that the correct value is set, otherwise the capacitors could be damaged.

## Configuring the capacitor stages:

There are two ways of configuring the capacitor stages. The stages can be configured manually or using the auto configuration mode. It is important to set the stage power correctly. The stage power can be looked up on the nameplate of the stage or the circuit diagram and then programmed manually. In this case, skip the menu item "Activate learning mode" and enter the power value individually for each stage.

## NOTE

If you cannot select the Learning mode menu item, check whether menu "On" is selected for "Learning mode" in the "Extras" menu.

If you want to activate the learning mode, make sure that all previous submenu parameters have been set correctly.
The learning mode is activated by pressing $\boldsymbol{\lambda}$. Change to $\mathrm{Y}= \pm$ by pressing ${ }^{2}$. and then to confirm.
After starting the learning mode, $\overline{-t i} \mathrm{y}$ e flashes and the remaining time until the end of the learning mode is displayed.

## NOTE

The auto configuration mode then sets the stage power automatically. However, this value has to be checked each time the learning process is completed.

### 8.7 Switching performance window:

$$
\begin{gathered}
\text { Suithmemprm } \\
\text { next } 4+
\end{gathered}
$$

Press $\boldsymbol{\nabla}$ to select submenus.
The settings for the switching performance by default (default settings) are displayed in the submenus of this window. These settings apply to most of the compensation systems.

## NOTE

Check all parameters to ensure that there are no deviations from the specifications made for this system.

The following submenus are available to affect the switching performance:

- Hysteresis switch-on (default setting 100\%, setting range 70 to 150\%): This value defines the controller switch-on criterion. This means the controller would switch on at $100 \%$ missing compensation power relative to the smallest capacitor stage of the system.
- Hysteresis switch-off (default setting 100\%, setting range 70 to 150\%): This value defines the controller switch-off criterion. This means the controller would switch off at $100 \%$ overcompensation power relative to the smallest capacitor stage of the system.
- Alarm delay (default setting 1200 seconds, setting range 0 to 3000 seconds): This value defines the time until the message PFC too small is displayed. If the set target cos phi is not reached, despite all available stages being switched on, this message is displayed after the set alarm delay time has elapsed.
- Idle time (default setting 30 seconds, setting range 0 to 300 seconds): This value defines the time the controller is idle after compensation before another switching operation is performed (connection or disconnection).
- Switching interval (default setting 8 seconds, setting range 0 to 10 seconds): This value defines the time the controller is always idle between two switching operations.
- Alarm cos phi (default setting ind. 0.92 , setting range ind. 0.70 to 1.0 ): This value is connected to the message PFC too small. If this value is not reached after the alarm delay has elapsed, despite all stages being switched on, the message PFC too small is displayed.
- Attenuation $\mathrm{Q}_{\text {miss }}$ (default settings 2, setting range 0 to 9): This value defines the attenuation of the display and control behavior to prevent rapid parameter changes if there is no compensation power.
- Attenuation U (default settings 2, setting range 0 to 9 ): This value defines the display attenuation to prevent rapid parameter changes of the measuring voltage.
- Attenuation I (default settings 2, setting range 0 to 9): This value defines the display attenuation to prevent rapid parameter changes of the measuring current.


### 8.8 Error message window:

$$
\begin{gathered}
\text { ME }=\Phi=\text { menu } \\
\text { next. } \%
\end{gathered}
$$

Press $\boldsymbol{\text { to select submenus. }}$
The possible messages, as well as the display configuration, are displayed in the submenus of this window.

The following error messages can be configured:

| Alarm submenu | Possible actions |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
|  |  |  |  |  |

If a submenu is selected (by pressing $\boldsymbol{\nabla}$ ), the error message dialog can be changed by pressing $\boldsymbol{\sim}$ to start entering values, 2 to change the settings and to save them.

## NOTE

The stage monitoring function (see Extras menu, Monitor stage power submenu) does not issue any messages, but marks the stages with an $\%$ (in the start menu window).

### 8.9 Extras window:

$$
\begin{aligned}
& \text { Extres } \\
& \text { next } 4 \rightarrow
\end{aligned}
$$

## Press $\boldsymbol{\nabla}$ to select submenus.

The additional possible settings are displayed in the submenus of this window,: If a submenu is selected (by pressing $\boldsymbol{\nabla}$ ), the settings can be changed by pressing $\boldsymbol{\lambda}$ to start entering values, ${ }^{2}$ to change the setting and to save it.

The following submenus are available:

- User language:

In this submenu, you can select the language for the LCD display (German, English, French or Spanish).

- THD limit:

The harmonic switch-off limit refers to the total of all measuring voltage harmonics (Lim THD). The programming range lies between 0 and 10\%. The setting can be adjusted in increments of $1 \%$. In addition, harmonics monitoring can also be disabled here (if the setting is Lim $=0 \%$, limit monitoring is deactivated). If voltage harmonics exceed the limit, an error message is displayed and a stage switch-off is performed.

- Operating cycle limit:

The limit of the capacitor contactor operating cycles is used as an indication to customers that the capacitor contactor could be worn out due to the number of switching operations accumulated. This message in no way influences the function of the compensation system. It is merely used as a "maintenance instruction". If the setting is Lim $=0 \%$, limit monitoring is deactivated but the operating cycle count is still activated.

- Sampling rate:

The power frequency tracing settings are displayed in this submenu. If the setting is "Auto", the sampling rate is traced automatically, within a range of 40 to 70 Hz . Alternatively, a fixed sampling rate of 50 Hz or 60 Hz can be set.

- Monitoring stage power:

The monitoring of the stage power can be activated or deactivated in this submenu. Only stages the stage power of which has been recorded in the learning mode are monitored. The manually configured stage power is not taken into account, as it is assumed that the stage power has been configured in accordance with the nameplate of the compensation stage.

- Functional principle:

Each time a capacitor stage is switched on, a check is performed to determine whether a change of current takes place in the main current transformer. If this is not the case, the stage is marked with an x in the start menu window. This may be for one of the following reasons and needs to be checked:

- Capacitor faulty
- Contactor faulty
- Fuse faulty


## - Reset:

The Reset menu item offers various methods of resetting the programmed controller parameters. The programmable parameters are reset to the default settings. This has the advantage that all configured parameters are deleted at the same time and the controller restarts with the default settings.

- Perform reset:

Extras menu, Reset menu item
Press $\boldsymbol{\lambda}=$ Reset flashes
Press $\boldsymbol{\lambda}$ and simultaneously = done is displayed
After about 2 seconds, the display shows Reset again

## NOTE

The resetting process can be interrupted by pressing $D$.

## - Contrast setting:

The contrast settings of the LCD can be changed in this submenu. Setting range: 0 to 10 .

- Brightness setting:

The LCD brightness can be changed in this submenu. Setting range: 0 to 9 .

- Dimmer brightness:

The LCD brightness reduction can be changed in this submenu. Setting range: 0 to 9 . The brightness is reduced after a set time of 15 minutes.

- Low-load limit:

In this submenu, the low-load detection limit can be changed to either 15 mA or 50 mA .

- Low-load delay:

The low-load detection delay time can be changed in this submenu. It can be varied between 1 and 60 minutes.

- Fan relay:

In this submenu, you can set the last stage relay (stage 6 or 12, depending on the device version) as a compensation stage relay or fan relay.

- Switching threshold for switching on fan:

In this submenu, the switching threshold for switching on the fan relay can be changed to between $0^{\circ} \mathrm{C}$ and $70^{\circ} \mathrm{C}$.

- Switching threshold for switching off fan:

In this submenu, the switching threshold for switching the fan relay off can be changed to between $0^{\circ} \mathrm{C}$ and $70^{\circ} \mathrm{C}$. To prevent unnecessary fan switching, a run-on time of 30 minutes is set.

- Switching threshold for system switch-off:

In this submenu, the switching threshold for switching off the system can be changed to between $0^{\circ} \mathrm{C}$ and $70^{\circ} \mathrm{C}$.

- Switching threshold for system switch-on:

In this submenu, the switching threshold for switching on the system can be changed to between $0^{\circ} \mathrm{C}$ and $70^{\circ} \mathrm{C}$.

- Bus mode:

In this submenu, the bus protocol of the device can be set to KBR eBus or Modbus RTU. If Modbus RTU is selected, you can set the transmission parameters now. The supported transmission parameters are:
Baud rate (Baud)
4800, 9600, 19200, 38400
Parity
Data bits
Stop bits
even, odd, none
8
1 for even and odd, 2 for Parity none
The KBR eBus setting is used for testing purposes.

- Learning mode:

In this submenu, you can show or hide the submenu item "Activate learning mode" (in the Commissioning menu).

- Key sounds:

In this submenu, you can turn the key sounds (which sound if a sensor button is pushed) on or off.

- Delete EEP:

For production purposes only.

## 9 Notes on troubleshooting

Undercompensation, not enough stages are switched on:
Check controller for error messages If the target $\cos \varphi$ is set to 0.8 capacitive, the capacitors need to start to be switched on. If the system is not over-dimensioned, almost all stages need to be switched on.

Check the system's main fuse and group fuses. All values are entered in the enclosed documents.

The group fuses must display at least 1.7 times the value of the capacitor power.
If the fuses blow despite being correctly selected, the groups must be checked individually for excessive current input and for defective contactors.

## Undercompensation, all stages are switched on:

The existing system is not sufficient (e.g. due to new inductive consumers). Please contact your local representative (enlarge your system). The service telephone number is given on the cover of these operating instructions.

Overcompensation, too many stages are switched on:
Check controller settings (target $\cos \varphi$ capacitive?).
Is the transformer connected in the wrong position?
Controller switches a lot, in particular during low load times
(at the weekend, at night):
Check the transformer ratio configuration. If required, (manually) switch a small stage on permanently.

NOTE

If the cause of the error cannot be found, please call your local representative. The phone number is given on the cover of this manual.

## 10 System and safety device maintenance

In order to ensure proper functioning and a long service life of your system, perform the following checks after commissioning the system and then on an annual basis.

- Check and re-tighten all connections. Screw connections may become loose at the beginning due to thermal stress.
- Check fuses, safety devices and switching equipment. Contactors are wearing parts. If the contactor is intact, switching must take place without excessive sparking.
- Check the control performance in automatic mode.
- Check the cooling air setting (fans, temperature monitoring function):
- Check if the controller temperature relay switches the fans on at $28^{\circ} \mathrm{C}$.
- Check if the temperature monitoring switches the system off via controller at $48^{\circ} \mathrm{C}$.
- Clean the filter mats if necessary, depending on how dirty they are.
- Perform a visual inspection of the capacitors.
- Examine the current input and capacitor terminal voltage once every three months.
- Check the reactive energy consumption by looking at the electricity bill.


NOTE

The current consumption and the temperature of these systems must be checked regularly so that an overload of the capacitors can be detected at an early stage. Excessive current consumption can be caused by an increasing proportion of harmonics or by faulty capacitors.

## 11 Technical data

### 11.1 Measuring and display values



### 11.2 Measuring accuracy

| Current | $\pm 0.5 \% / \pm 1$ digit (for 0.1 to 5 A ) |
| :--- | :--- |
| Voltage | $\pm 0.5 \% / \pm 1$ digit |
| Power | $\pm 1 \% / \pm 1$ digit |
| Power factor | $\pm 1 \% / \pm 1$ digit |
| Frequency | $\pm 0.1 \% / \pm 1$ digit |
| Temperature | $\pm 2^{\circ} \mathrm{C} / \pm 1$ digit |

### 11.3 Measuring principle

| Sampling | 128 readings per period |
| :--- | :--- |
| A/D converter | 12 bit |
| Measurement of V and I | Simultaneous recording of U and I <br> readings |
| Measuring cycle | 20 ms |
| Harmonics calculation | FFT with 128 points over one period |
| Frequency measurement | Consumption: Voltage measurement <br> between phase Lx $-\mathrm{N} / \mathrm{Ly})$ |
| Temperature sensor | Analog measurement with PT 1000 |

### 11.4 Device memory

| Data memory | 16 kB RAM (volatile) |
| :--- | :--- |
| Program and parameter memory | 128 kB flash |
| Extreme values (max.) | Miss. compensation power $\mathrm{Q}_{\max }$ |

### 11.5 Other limits:

| Limit violations: |  |
| :--- | :--- |
| Harmonics | Acquisition time approx. 100 ms |
| Overvoltage switch-off: | Acquisition time approx. 40 ms |
| Zero-voltage switch-off: | Acquisition time approx. 40 ms <br> (for measuring voltage) |

### 11.6 Power supply

| Power supply | $100-240 \mathrm{~V}+/-10 \% \mathrm{DC} / 50 / 60 \mathrm{HZ}$ |
| :--- | :--- |

### 11.7 Hardware inputs and outputs

### 11.7.1 Hardware inputs

| Voltage <br> measuring <br> input | $\mathrm{U}_{\mathrm{PH}-\mathrm{N}}$ or $\mathrm{U}_{\mathrm{PH}-\mathrm{PH}}$ | $30-690$ VAC <br> (max. permissible value: 790 VAC ) |
| :--- | :--- | :--- |
|  | Input impedance | 750 kOhm |
|  | Measuring range | 1 measuring range, measuring voltage <br> transformer can be configured |
| Current <br> measuring <br> input | $\mathrm{I}_{\mathrm{L} 1}$ or $\mathrm{I}_{\mathrm{L} 2}$ or $\mathrm{I}_{\mathrm{L} 3}$ | $0.015-5 \mathrm{~A}$ (max. permissible value: 6 A ) |
|  | Power consumption | 0.3 VA at $6 \mathrm{~A}, 0.05 \mathrm{VA}$ at 1.2 A |
|  | Measuring range | 1 measuring range, current transformer can <br> be configured |
| Analog input | PT 1000 measurement <br> sensor | Temperature measurement $-10^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}$, <br> $+/-2{ }^{\circ} \mathrm{C}$ max. length of connecting cables $<$ <br> 3 meters |

### 11.7.2 Hardware outputs

| Alarm relay | Switching capacity | $250 \mathrm{~V}(\mathrm{AC}) / 2$ A floating |
| :--- | :--- | :--- |
| Capacitor stage <br> relay | Switching capacity | $250 \mathrm{~V}(\mathrm{AC}) / 2$ A floating |
| Serial interface | BUS | RS485 for connection to the Modbus |
|  | Protocol, baud rate | Modbus RTU; baud rate 4800, 9600, 19200; <br> 38400 Parity none, even, odd |
|  | Addressing | Modbus: manual on the device, <br> address 1 to 247 |

### 11.8 Electrical connection

| Connection elements | Plug terminals |  |
| :--- | :--- | :--- |
| Permissible cross section <br> of the connection lines | $2.5 \mathrm{~mm}^{2}$ |  |
| Measuring <br> voltage inputs | Fuse protection | max. 6 A |
| Measuring <br> current input | Fuse protection | NONE!!! Always short-circuit current trans- <br> former terminals k and I before opening the <br> circuit! |
| Input supply <br> voltage | Fuse protection | max. 6 A |
| BUS <br> connection | Connection material | To ensure proper operation, only use <br> shielded twisted-pair cables; e.g. I-Y(St)Y EIB <br> $2 \times 2 \times 0.8$ |
| Relay output | Fuse protection | max 2 A medium time-lag |
| Transformer <br> connection | Connections | See wiring diagram |
| Interface <br> connection | Pins for BUS <br> connection via RS-485 | Terminal 90 \& $\perp$ <br> Terminal 91 A <br> Terminal 92 B |

### 11.9 Mechanical data

| Switchboard <br> installation | Housing dimensions | $144 \times 144 \times 60 \mathrm{~mm}(\mathrm{H} \times \mathrm{W} \times \mathrm{D})$, |
| :--- | :--- | :--- |
|  | Installation cut-out | $138 \times 138 \mathrm{~mm}$ |
|  | Weight | Approx. 650 g |

### 11.10 Standards and miscellaneous

| Ambient conditions | Standards | DIN EN 60721-3-3:1995-09 + <br> DIN EN 60721-3-3/A2:1997-07; $3 \mathrm{~K} 5+3 \mathrm{Z} 11 ;$ <br> (IEC721-3-3;3K5+3Z11) |
| :---: | :---: | :---: |
|  | Operating temperature | $-5^{\circ} \mathrm{C}-.+55^{\circ} \mathrm{C}$ |
|  | Humidity | 5\%-95\% non-condensing |
|  | Storage temperature | $-25^{\circ} \mathrm{C}-.+70^{\circ} \mathrm{C}$ |
|  | Operating altitude | up to max. 2000 m above sea level |
| Electrical safety | Standards | DIN EN 61010-1:2011-07; <br> DIN EN 61010-2-030:2011-07 |
|  | Protection class | I |
|  | Overvoltage category, measurement category | III |
| Protection type | Standards | DIN EN 60529:2014-09 |
|  | Front | IP 51 (with optional front door max. IP 54) |
|  | Terminals | IP 20 |
| EMC | Standards | DIN EN 61000-6-2:2006-03 + amendment 1:2011-06 DIN EN 61000-6-3:2011-09 + amendment 1:2012-11 |

## 12 Selection of cables and fuses

| C power (400 V) Q (kvar) | Current consumption I (A) per phase | Supply cable $\mathrm{Cu}\left(\mathrm{mm}^{2}\right)$ | Fuse (slow-blow) $3 \times I(A)$ |
| :---: | :---: | :---: | :---: |
| 0.5 | 0.72 | $4 \mathrm{x} \quad 1.5$ | 10 |
| 1 | 1.44 | $4 \mathrm{x} \quad 1.5$ | 10 |
| 1.5 | 2.16 | $4 \mathrm{x} \quad 1.5$ | 10 |
| 2 | 2.88 | $4 \mathrm{x} \quad 1.5$ | 10 |
| 2.5 | 3.60 | $4 \mathrm{x} \quad 1.5$ | 10 |
| 3 | 4.32 | $4 \mathrm{x} \quad 1.5$ | 10 |
| 4 | 5.76 | $4 \mathrm{x} \quad 1.5$ | 10 |
| 5 | 7.20 | $4 \mathrm{x} \quad 2.5$ | 16 |
| 6 | 8.64 | $4 \mathrm{x} \quad 2.5$ | 16 |
| 7.5 | 10.80 | $4 \mathrm{x} \quad 2.5$ | 16 |
| 10 | 14.40 | $4 \mathrm{x} \quad 2.5$ | 25 |
| 12.5 | 18.00 | $4 \mathrm{x} \quad 6$ | 35 |
| 15 | 21.60 | $4 \times 10$ | 35 |
| 16.7 | 24.00 | $4 \times 10$ | 35 |
| 20 | 28.80 | $4 \times 10$ | 50 |
| 25 | 36.00 | $4 \times 16$ | 63 |
| 30 | 43.20 | $4 \times 16$ | 80 |
| 33.3 | 48.00 | $4 \times 16$ | 80 |
| 35 | 50.40 | $4 \times 25$ | 80 |
| 40 | 57.60 | $4 \times 25$ | 100 |
| 45 | 64.80 | $3 \times 35 / 16$ | 100 |
| 50 | 72.00 | $3 \times 50 / 25$ | 125 |
| 60 | 86.40 | $3 \times 50 / 25$ | 125 |
| 70 | 100.80 | $3 \times 70 / 35$ | 160 |
| 75 | 108.00 | $3 \times 70 / 35$ | 160 |
| 80 | 115.10 | $3 \times 95 / 50$ | 200 |
| 90 | 129.60 | $3 \times 95 / 50$ | 200 |
| 100 | 144.00 | $3 \times 95 / 50$ | 250 |
| 120 | 172.80 | $3 x \quad 120 / 70$ | 250 |
| 125 | 180.00 | $3 x \quad 120 / 70$ | 250 |
| 150 | 216.00 | $3 \times 150 / 70$ | 315 |
| 180 | 259.20 | $3 \times 240 / 120$ | 400 |
| 200 | 288.00 | $3 \times 240 / 120$ | 400 |
| 250 | 360.00 | $2 \times 3 \times 150 / 70$ | 500 |
| 300 | 432.00 | $2 \times 3 \times 185 / 95$ | 630 |
| 350 | 504.00 | $2 \times 3 \times 240 / 120$ | $2 \times 400$ |
| 400 | 576.00 | $2 \times 3 \times 240 / 120$ | $2 \times 400$ |
| 450 | 648.00 | $4 \times 3 \times 120 / 70$ | $2 \times 500$ |
| 500 | 720.00 | $4 \times 3 \times 150 / 70$ | $2 \times 500$ |

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## 13 Data point description for the Modbus protocol

## multicomp F144-3

13.1 Supported Modbus commands
13.2 Data formats
13.3 Interface parameters
13.4 Device settings
13.5 Data points
13.6 Device information

### 13.1 Supported Modbus commands

| $0 \times 04$ | Read input registers |
| :--- | :--- |
| $0 \times 2 B$ | Read device identification |

The multicomp F144-3 does not support broadcast commands. All Modbus commands described are device-specific commands.

### 13.2 Data formats

(unsigned) short: 0x1234

| Address | +0 | +1 |  |  |
| :--- | :--- | :--- | :--- | :--- |
| Contents | $0 \times 12$ | $0 \times 34$ |  |  |

Rule for byte sequence: MSB before LSB
(unsigned) long: 0x12345678

| Address | +0 | +1 | +2 | +3 |
| :--- | :--- | :--- | :--- | :--- |
| Contents | $0 \times 12$ | $0 \times 34$ | $0 \times 56$ | $0 \times 78$ |

Rule for byte sequence: MSB before LSB
float:

| Format | corresponds to the IEEE 754 standard |
| :--- | :--- |
| Representation | 4 bytes |
| Accuracy | 24 bits ( $>$ represent $>7$ decimal points) |
| Composition | 24 -bit mantissa; 8-bit exponent |
| Mantissa | 24 bits (M) + 1 bit (S) |
| Exponent | The MSB of the mantissa is always $1=>$ it is not saved <br> separately! $S=$ sign of the mantissa: $S=1>$ negative <br> number; $S=0>$ positive number |
| Exponent | 8 bits ( $0-255$ ); is saved relatively to 127, i.e. the current <br> value of the exponent is calculated by subtracting the <br> number 127 from the saved value. <br> Curr. exp. $=$ saved exp value. -127 <br> => range from 128 to -127! |

Example 1: -12.5 decimal $=0 x C 1480000$ hex
M: 24 bit-mantissa
E: Exponent with offset of 127
S : Sign for mantissa ( $\mathrm{S}=1$ neg.; $\mathrm{S}=0$ pos.)

| Address | +0 | +1 | +2 | +3 |
| :--- | :--- | :--- | :--- | :--- |
| Format | SEEEEEEE | EMMMMMMM | MMMMMMMM | MMMMMMMM |
| Binary | 11000001 | 01001000 | 00000000 | 00000000 |
| Hex | C1 | 48 | 00 | 00 |

The byte sequence is defined as follows:
The byte with the " S sign bit" is transmitted as the first byte over the bus.
The sequence of the float bytes of the bus can be reversed, if necessary, using the device parameter 0xD02C (see table 1).
The register value 0xD02C in this case means:

- with 1 -> sign bit S in 1st byte (sequence as defined)
- with 0 -> sign bit $S$ in 4th byte (sequence reversed)

The following information can be derived from this:
The sign bit is $1=>$ negative mantissa
The value of the exponent amounts to 10000010 bin or 130 dec .
This results in an exponent value of: 130-127=3
The mantissa has the following value: 10010000000000000000000
The decimal point can be found at the left end of the mantissa, preceded by a 1. This position does not appear in the hexadecimal numeric notation. If you add 1 and set the decimal point at the beginning of the mantissa, the following value is obtained:

### 1.10010000000000000000000

Now, the mantissa needs to be adjusted to the exponent. A negative exponent shifts the decimal point to the left, a positive exponent shifts it to the right. Since the exponent is 3 , this appears in our representation as: 1100.10000000000000000000

The number obtained corresponds to the binary floating-point number.
Binary digits to the left of the decimal point result in values $>1$. In this example, 1100 bin yields the number $12 \mathrm{dec} .\{(1 \times 23)+(1 \times 22)+(0 \times 21)+(0 \times 20)\}$
Binary digits to the right of the decimal point result in values $<1$. In this example, .100....... bin results in the number 0.5 dec. $\{(1 \times 2-1)+(0 \times 2-2)+(0 \times 2-3)+$ (0x2-4)\}
By adding the individual values, 12.5 is obtained. As the sign bit was set, it is a negative value, -12.5 . The hexadecimal number 0xC1480000 thus corresponds to -12.5.

Example 2: -12.55155 decimal $=0 x C 148$ D325 hex

| Address | +0 | +1 | +2 | +3 |
| :--- | :--- | :--- | :--- | :--- |
| Format | SEEEEEEE | EMMMMMMM | MMMMMMMM | MMMMMMMM |
| Binary | 11000001 | 01001000 | 11010011 | 00100101 |
| Hex | C1 | 48 | D3 | 25 |

Example 3: 45.354 decimal $=0 \times 42356$ A7F hex

| Address | +0 | +1 | +2 | +3 |
| :--- | :--- | :--- | :--- | :--- |
| Format | SEEEEEEE | EMMMMMMM | MMMMMMMM | MMMMMMMM |
| Binary | 01000010 | 00110101 | 01101010 | 01111111 |
| Hex | 42 | 35 | AA | 7F |

Exponent: 10000100 bin = 132 dec .

$$
>\text { Exp. }=132-127=5
$$

Mantissa: $\mathrm{S}=0$
$>$ Sign=positive
01101010110101001111111 bin
Decimal point added to the first position of the mantissa
$>01101010110101001111111$
Leading 1 in front of the decimal point
$>1.01101010110101001111111$
Taking the exponent into account (=5)
$>101101.010110101001111111$
to the left of the decimal point: 101101 bin $=25+23+22+20=$
45 dec.
To the right of the decimal point: $\quad 010110101001111111$ bin $=$
$2-2+2-4+2-5+2-7+2-9+2-12+2-13+2-14+2-15+2-16+2-17+$
$2-18=0.3540001$ dec
Final result: +45.03540001 dec.

### 13.3 Interface parameters

| Baud rate (Baud) | Parity | Data bits | Stop bits |
| :--- | :--- | :--- | :--- |
| $4800,9600,19200$, <br> 38400 | even, odd, none | 8 | 2 for parity none, <br> otherwise 1 |

The maximum data length of a Modbus transmission is 256 bytes. This results in a user data length of 253 bytes.

The number of data bits and stop bits is defined in the Modbus definition. Baud rates of less than 4800 baud are possible by definition, but not implemented at the moment. The interface parameters can only be configured on the device (not via bus).

### 13.4 Device settings

The settings are read with the $0 \times 04$ command (read input registers) in accordance with table 1 . Writing is not possible at present.

| Address | Words | Description | Value | Format |
| :---: | :---: | :---: | :---: | :---: |
| 0xD002 | 2 | Primary transformer measuring voltage | 0-999999 V | float |
| 0xD004 | 2 | Secondary transformer measuring voltage | 0-999 V | float |
| 0xD006 | 2 | Primary transformer measuring current | 0-999999 A | float |
| 0xD008 | 2 | Secondary transformer measuring current | $1 \mathrm{~A} / 5 \mathrm{~A}$ | float |
| 0xD00 A | 2 | Target CosPhi 1 | $-1.0-+1.0$ | float |
| 0xD00C | 2 |  |  | float |
| 0xD00E | 2 | Target CosPhi for energy recovery (fixed setting) | $-1.0-+1.0$ | float |
| 0xD010 | 2 | Target CosPhi for message "PFC too small" | $-1.0-+1.0$ | float |
| 0xD012 | 2 | Connected phase voltage measurement | $\begin{aligned} & \hline 0=\mathrm{L} 1 \mathrm{~N} / / 1=\mathrm{L} 2 \mathrm{~N} \\ & / / 2=\mathrm{L} 3 \mathrm{~N} / / 4=\mathrm{L} 12 \\ & / / 5=\mathrm{L} 23 / / 6=\mathrm{L} 31 \end{aligned}$ | unsigned long |
| 0xD014 | 2 | Connected phase current measurement | $\begin{aligned} & 0=\mathrm{L} 1 / / 1=\mathrm{L} 2 / / \\ & 2=\mathrm{L} 3 / / 3=-\mathrm{L} 1 / / \\ & 4=-\mathrm{L} 2 / / 5=-\mathrm{L} 3 \end{aligned}$ | unsigned long |
| 0xD016 | 2 |  |  |  |
| 0xD018 | 2 |  |  |  |
| 0xD01a | 2 |  |  |  |
| 0xD01c | 2 |  |  |  |
| 0xD01e | 2 | General |  |  |



| Address | Words | Description | Value | Format |
| :---: | :---: | :---: | :---: | :---: |
| 0xD04E | 2 |  |  | unsigned long |
| 0xD050 | 2 |  |  | unsigned long |
| 0xD052 | 2 | Attenuation coefficient for voltage | 0-9 | unsigned long |
| 0xD054 | 2 | Attenuation coefficient for current | 0-9 | unsigned long |
| 0xD056 | 2 | Attenuation coefficient $\mathrm{Q}_{\text {miss }}$ | 0-9 | unsigned long |
| 0xD058 | 2 |  |  |  |
| 0xd05A | 2 |  |  |  |
| 0xD05C | 2 |  |  |  |
| 0xD05E | 2 |  |  |  |
| 0xD060 | 2 | Extras |  |  |
| 0xD062 | 2 | Limit for operating cycle message | 0-999999 | unsigned long |
| 0xD064 | 2 | Low-load limit [A] | 0.015 or 0.05 | float |
| 0xD066 | 2 | Time until low-load switch-off in minutes | 1-60 | unsigned long |
| 0xD068 | 2 |  |  | unsigned long |
| 0xD06A | 2 | Voltage harmonic limit [\%] | 0-10 | unsigned long |
| 0xD06C | 2 |  |  | unsigned long |
| 0xD06E | 2 | Modbus address | 1-247 | unsigned long |
| 0xD070 | 2 | Modbus parameters $\begin{array}{\|l} (0=\mathrm{e} 4800 / / 1=04800 / / 2=n 4800 / / \\ 3=\mathrm{e} 9600 / / 4=09600 / / / 5=n 9600 / / \\ 6=\mathrm{e} 19200 / / 7=\mathrm{o} 19200 / / 8=n 19200 / / \\ 9=\mathrm{e} 38400 / / 10=038400 / / 11=\mathrm{n} 38400) \end{array}$ | 0-11 | unsigned long |
| 0xD072 | 2 |  |  |  |
| 0xD074 | 2 |  |  |  |
| 0xD076 | 2 |  |  |  |
| 0xD078 | 2 |  |  |  |
| 0xD07A | 2 |  |  |  |
| 0xD07C | 2 |  |  |  |



KBR multicomp F144-3 6RO/12RO

| Address | Words | Description | Value | Format |
| :---: | :---: | :---: | :---: | :---: |
| 0xD0C0 | 2 | Base index for the following stage parameters <br> (addresses 0xD0C0 to 0xDOCE) | 4 (= stage 5) | unsigned long |
| 0xD0CE | 2 |  | 0 | unsigned long |
| 0xD0D0 | 2 | Base index for the following stage parameters <br> (addresses 0xD0D0 to 0xD0DE) | 5 (= stage 6) | unsigned long |
| 0xDODE | 2 |  | 0 | unsigned long |
| 0xD0E0 | 2 | Base index for the following stage parameters (addresses 0xDOEO to 0xDOEE) | 6 (= stage 7) | unsigned long |
| 0xD0EE | 2 |  | 0 | unsigned long |
| 0xD0F0 | 2 | Base index for the following stage parameters <br> (addresses 0xDOF0 to 0xDOFE) | 7 (= stage 8) | unsigned long |
| 0xD0FE | 2 |  | 0 | unsigned long |
| 0xD100 | 2 | Base index for the following stage parameters (addresses 0xD100 to 0xD10E) | 8 (= stage 9) | unsigned long |
| 0xD10E | 2 |  | 0 | unsigned long |
| 0xD110 | 2 | Base index for the following stage parameters (addresses 0xD110 to 0xD11E) | 9 (= stage 10) | unsigned long |

\(\left.$$
\begin{array}{|l|l|l|l|l|}\hline \text { Address } & \text { Words } & \text { Description } & \text { Value } & \text { Format } \\
\hline \text { 0xD11E } & 2 & & 0 & \begin{array}{l}\text { unsigned } \\
\text { long }\end{array} \\
\hline & & & \begin{array}{l}\text { Base index for the following stage } \\
\text { parameters } \\
\text { (addresses 0xD120 to 0xD12E) }\end{array} & 10 \text { (= stage 11) }\end{array}
$$ \begin{array}{l}unsigned <br>

long\end{array}\right] |\)| 0xD120 |
| :--- |
| 2 |

## Request:

0104 D0 010002 xx xx
in which

| 01 | Device address |
| :--- | :--- |
| 04 | Command |
| D0 01 | Read from register 0xD002 "Measuring voltage primary transformer" (in <br> accordance with the Modbus definition, the required address must be set <br> to -1 in the request telex) |
| 0002 | Read 2 registers, i.e. read 1 data point |
| $x x x x$ | CRC code |

## Response:

010404 xx xx xx xx yy yy
in which

| 01 | Device address |  |
| :--- | :--- | :--- |
| 04 | Command |  |
| 04 | 4 data bytes |  |
| $x x x x x x x x$ | Measuring voltage primary transformer | 400 V |
| $y y y y$ | CRC code |  |

### 13.5 Data points

| Address | Words | Description | Unit | Format |
| :---: | :---: | :---: | :---: | :---: |
| 0x0002 | 2 | Voltage | V | float |
| 0x0004 | 2 | Current | A | float |
| 0x0006 | 2 | Network frequency | Hz | float |
| 0x0008 | 2 | Current CosPhi |  | float |
| 0x000a | 2 | Active power | W | float |
| 0x000c | 2 | Fundamental reactive power | var | float |
| 0x000e | 2 | Missing compensation power | var | float |
| 0x0010 | 2 | Apparent power | VA | float |
| $0 \times 0012$ | 2 | THD | \% | float |
| 0x0014 | 2 | Temperature | ${ }^{\circ} \mathrm{C}$ | float |
| $0 \times 0016$ | 2 | Overtemperature switch-off |  | float |
| $0 \times 0018$ | 2 | Voltage $3^{\text {rd }}$ harmonic | \% | float |
| 0x001a | 2 | Voltage $5^{\text {th }}$ harmonic | \% | float |
| 0x001c | 2 | Voltage $7^{\text {th }}$ harmonic | \% | float |
| 0x001e | 2 | Voltage 9 ${ }^{\text {th }}$ harmonic | \% | float |
| 0x0020 | 2 | Voltage 11 ${ }^{\text {th }}$ harmonic | \% | float |
| 0x0022 | 2 | Voltage 13 ${ }^{\text {th }}$ harmonic | \% | float |
| 0x0024 | 2 | Maximum missing compensation power | var | float |
| 0x0026 | 2 | Relay states ( 12 bit: bit $0=$ stage 1 - bit 11 = stage $12 / /$ bit $13=$ error message) | bitwise | unsigned long |
| 0x0028 | 2 | Messages (bit coded) |  | unsigned long |
| 0x002a | 2 | Error messages (bit coded) |  | unsigned long |
|  |  |  |  |  |


| Messages: | Bit 00 set: | No stage power |
| :--- | :--- | :--- |
| (display) | Bit 01 set: | System temperature switch-off |
|  | Bit 02 set: | No measuring current |
|  | Bit 03 set: | No measuring voltage |
|  | Bit 04 set: | Low load operation |
|  | Bit 05 set: | Voltage harmonics limit reached |
|  | Bit 06 set: | Operating cycle limit reached |
|  | Bit 07 set: | PFC too small |
|  |  |  |
| Error messages: | Bit 00 set: | No stage power |
| (relay set) | Bit 01 set: | System temperature switch-off |
|  | Bit 02 set: | No measuring current |
|  | Bit 03 set: | No measuring voltage |
|  | Bit 04 set: | Low load operation |
|  | Bit 05 set: | Voltage harmonics limit reached |
|  | Bit 06 set: | Operating cycle limit reached |
|  | Bit 07 set: | PFC too small |

## Example Modbus RTU

Request:
010400 1F 00324019
where

| 01 | Device address |
| :--- | :--- |
| 04 | Command |
| 0001 | Read voltage from register 0x0002 <br> (in accordance with Modbus definition, the required address <br> must be set to -1 in the request telex) |
| 0026 | Read 38 registers, i.e. read 19 data points |
| 4019 | CRC code |

## Response:

$010464 \mathrm{xx} x \mathrm{x}$ xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx xx
 XX XX XX XX XX XX XX
 $x x$ xx xx yy yy
where

| 01 | Device address |  |
| :---: | :---: | :---: |
| 04 | Command |  |
| 4C | 76 data bytes |  |
| xx xx xx xx | Voltage | xx V |
| xx $x$ x $x$ x $x$ x | Current | xx A |
| xx xx xx xx | Network frequency | xx Hz |
| xx xx xx xx | Current CosPhi | xx |
| XX XX XX XX | Active power | xx W |
| xx xx xx xx | Fundamental reactive power | xx var |
| $x \mathrm{xxx} \mathrm{xxxx}$ | Missing compensation power | xx var |
| xx xx xx xx | Apparent power | xx VA |
| xx xx xx xx | THD | xx \% |
|  | Temperature | $x x^{\circ} \mathrm{C}$ |
|  | Overtemperature switch-off | XX |
| XX XX XX XX | Voltage $3^{\text {rd }}$ harmonic | xx \% |
| $x \mathrm{xxx} \mathrm{xx} \mathrm{xx}$ | Voltage 5 ${ }^{\text {rd }}$ harmonic | xx \% |
| XX XX XX XX | Voltage 7rd harmonic | xx \% |
| $x \mathrm{xxx} \mathrm{xx} \mathrm{xx}$ | Voltage 9rd harmonic | xx \% |
| XX XX XX XX | Voltage 11rd harmonic | xx \% |


| $x x x x x x x x$ | Voltage $13^{\text {rd }}$ harmonic | $x x \%$ |
| :--- | :--- | :--- |
| $x x x x x x x x$ | Maximum missing compensation power | $x x$ var |
| $x x x x x x x x$ | Relay states (12 bit: bit $0=$ stage $1-$ bit $11=$ <br> stage $12 / /$ bit $13=$ error message) | $x x$ |
| $y y y y$ | CRC code |  |

### 13.6 Device information

The device information is read via the command 0x2B (Read Device Identification)

Information about the manufacturer, device code and device version is read in the process. The device supplies the "Basic Device Identification". "Regular" and "Extended Device Identification" are optional according to the Modbus definition.

## Example Modbus RTU

Request:
01 2B 0E 01007077
in which

| 01 | Device address |
| :--- | :--- |
| $2 B$ | Command |
| $0 E$ | MEl type according to the Modbus definition always 0x0E |
| 01 | Device ID Code for "Basic Device Identification" (see Modbus <br> definition) |
| 00 | Object ID -> in our example manufacturer name, product name <br> and version |
| 7077 | CRC code |

## Response:

01 2B 0E 01010000030008 4B 42522047 6D 62480112 4D 75 6C 74 69 6D
6573732043 6F 6D 66
6F 727402092032 2E 303072313030 yy yy

| 01 | Device address |
| :---: | :---: |
| 2B | Command |
| OE | MEI type (see Modbus definition) |
| 01 | "Basic identification" (see Modbus definition) |
| 01 | "Conformity level" (see Modbus definition) |
| 00 | No further information follows (no additional telex required) |
| 00 | Next object ID |
| 03 | Number of objects |
| 00 | Object ID 00 |
| 08 | Length of the text of ID 00 |
| $\begin{aligned} & \text { 4B } 42522047 \text { 6D } 62 \\ & \text { 48 } \end{aligned}$ | "KBR GmbH" |
| 01 | Object ID 01 |
| 12 | Length of the text of ID 01 |
| 6D 75 6C 746963 6F 6D 702046313434 1D 332020 | "multicomp F144-3" |
| 02 | Object ID 02 |
| 09 | Length of the text of ID 02 |
| $\begin{aligned} & 2032 \text { 2E } 30307231 \\ & 3030 \end{aligned}$ | "2.00r100" |
| yy yy | CRC code |

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